

VISION PAR ORDINATEUR

PROJECT

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| Lecturers: 16 | TC: 0.0 | PW: 0.0 | Autonomy: 0.0 | Study: 4 | Project: 0.0 | Language: FR

Objectives

Computer vision aims to model and automate the visual recognition process by the machine and has many applications (e.g., industrial inspection, robotic navigation, human-machine interaction, etc.). This course introduces the key concepts and techniques of the field and covers the following topics: image formation and filtering, contour detection and segmentation, local descriptors and their matching, stereovision, movement and structure estimation, detection and recognition of objects.

Keywords: Image Filtering and processing, edge detection and segmentation, local descriptors, motion tracking, stereo vision, object detection and recognition

Programme

- Introduction to Computer Vision
- Reminders on image formation and filtering, contour detection by variational techniques
- Reminders on homogeneous coordinates and geometric transformation
- Projective Geometry
- Segmentation of images and objects
- Local Feature's Descriptors and Matching
- Movement tracking and structure estimation
- Camera Calibration and Stereo Vision
- Object detection and recognition

Learning outcomes

- · Understand the process of image formation and stereovision
- To be able to implement fundamental techniques to improve and process images
- Develop vision applications for the detection of simple objects

Independent study

Objectifs: This activity is not concerned with framed autonomy activities outside personal work.

Méhodes: This activity is not concerned with framed autonomy activities outside personal work.

Core texts

D. Forsyth, J. Ponce., COMPUTER VISION -- A MODERN APPROACH., Prentice Hall., 2002
R. Szeliski. COMPUTER VISION -- ALGORITHMS AND APPLICATIONS, Springer, 2010
R. Hartley, A. Zisserman. MULTIPLE VIEW GEOMETRY IN COMPUTER VISION., Cambridge University Press, 2004

Assessment

The final test and scores of BE